



Modeling Free Space Optical Systems

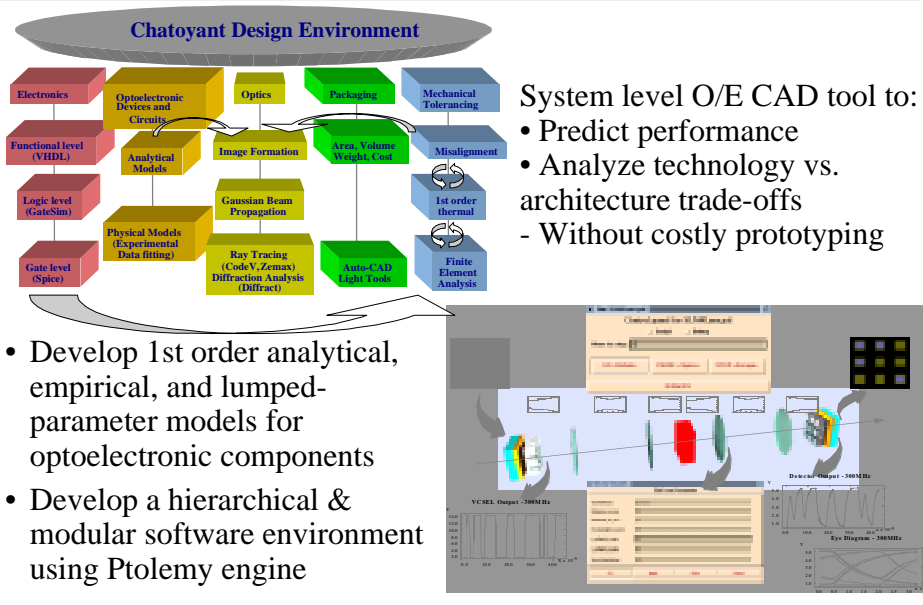
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Chatoyant - Goals & Methods

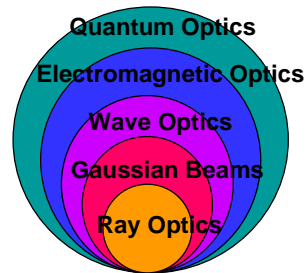




Models of Optical/Electronic Signals



- Messages are arrays of O/E signals
- Piece-wise linear **Intensity** or **Voltage**
- **Gaussian shape, angle, position, wavelength, polarization**
- **Source impedance**
- Variable time step (Δt)
 - discrete, continuous, PWL



Lumped parameter models

B.E.A. Saleh and M. Teich, *Fundamentals of Photonics*, Wiley, 1991

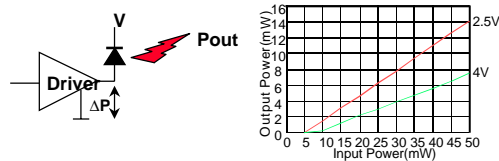


Models of Components

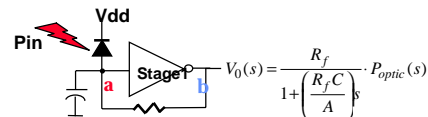


- Analytic models
 - Physics based
- Empirical models
 - Experimental data fitting
- Derived models
 - Parametric models extracted from or verified by lower level tools

$$I(r, z) = I_0 \left[\frac{W_0}{W(z)} \right]^2 \exp \left[-\frac{2r^2}{W^2(z)} \right]$$



$$P_{out} = \frac{\eta_{L1}/V_{th}}{(1-\eta_{L1}/V_{th})} (P_{in} - I_{th}V_{th})$$

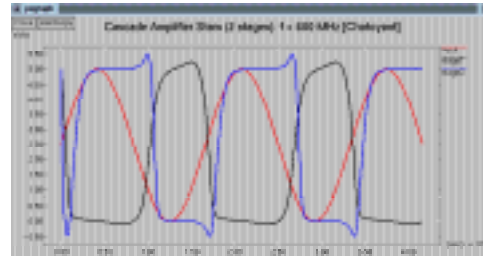




Piecewise Linear Model for Time



- **Motivation:**
 - Modeling dynamic response is necessary.
- **Problem:**
 - Small signal model analysis is invalid
- **Solution:**
 - Use a mixture of analytic and lumped-parameter models
 - CMOS Large Signal Models
- **Advantages:**
 - Dynamic time resolution achieves high accuracy at low computation cost
 - Homogeneous simulation environment



— Input — Stage 1 Output — Stage 2 Output

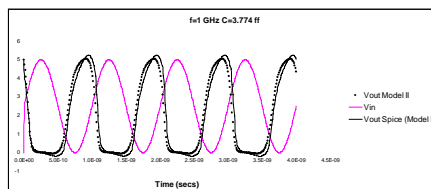
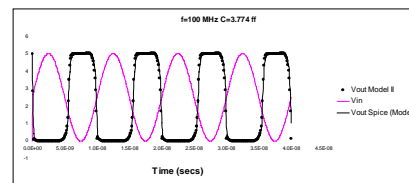
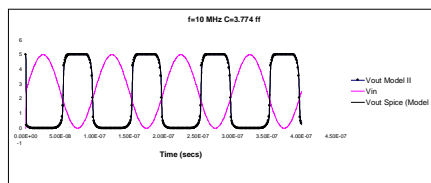
High frequency response in Chatoyant for a cascade driver configuration ($f = 600 \text{ MHz}$ & $C_{ld} = 1\text{fF}$).



Electrical Drivers (Tests)



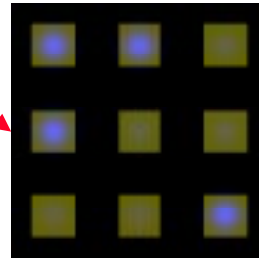
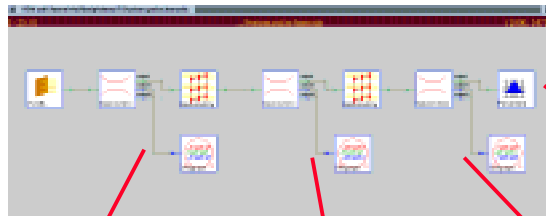
	f= 10 MHz C=3.774ff			f= 100 MHz C=3.774ff			f= 1 GHz C=3.774ff		
	Spice Level 2	Model I	Model II	Spice Level 2	Model I	Model II	Spice Level 2	Model I	Model II
Speed									
Time	0.13	0.093	0.15	0.12	0.089	0.091	0.12	0.094	0.089
Iterations	307	100	200	313	100	100	300	100	100
Accuracy	0	9.1%/18.8 SD	1.8%/4.7 SD	0	3.4%/6.8 SD	3.3%/6.7 SD	0	10%/12.9SD	9.99%/13.8SD



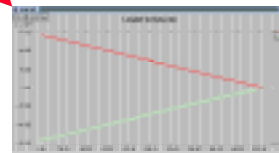
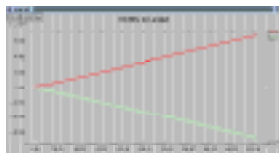
The times for the models include the computational load of the whole system (Chatoyant Implementation).



Static Simulation of Gaussian Beam Propagation



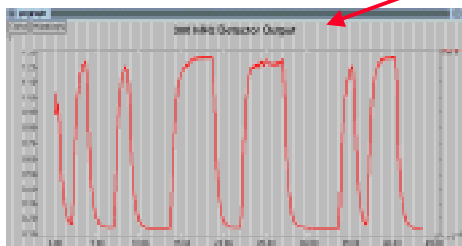
Gaussian Beams On Detector Array



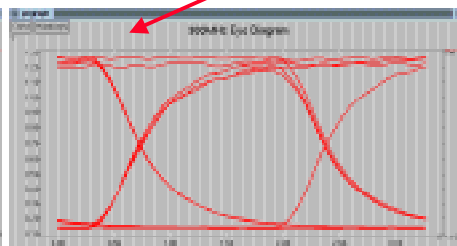
Gaussian Beam propagation



Dynamic Simulation: Detector Response



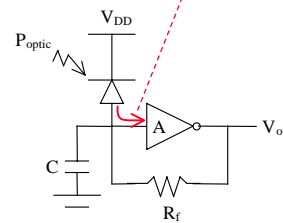
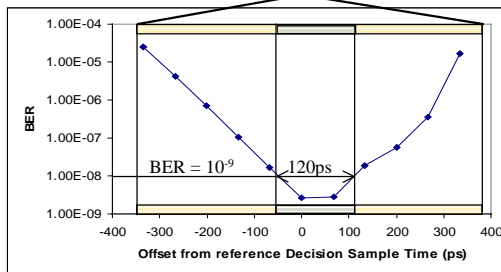
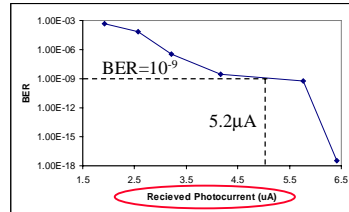
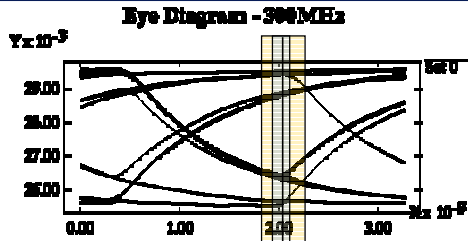
Detector Output



Eye Diagram



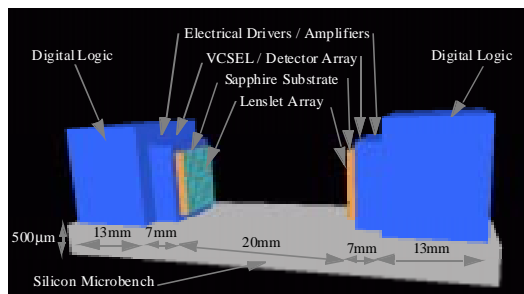
BER Modeling



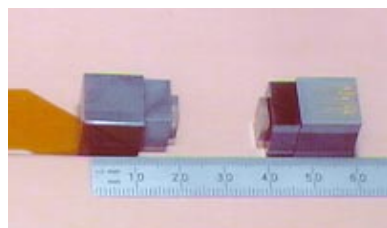
Krishnamoorthy, A.V., Woodward, T.K., Goossen, et. al
 "Operation of a Single-Ended 550Mbit/s, 41fJ, Hybrid CMOS/MQW Receiver-transmitter", Electronic Letters, April 1996.



System 1: 3D OESP / FFT Demo Prototype



μ Bench Assembly



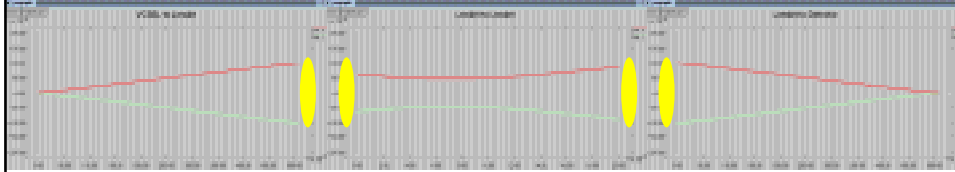
Function: FFT
 512x512
 32 bits complex
 Throughput < 1 msec
 Power < 340 W
 Volume < 35 cm³



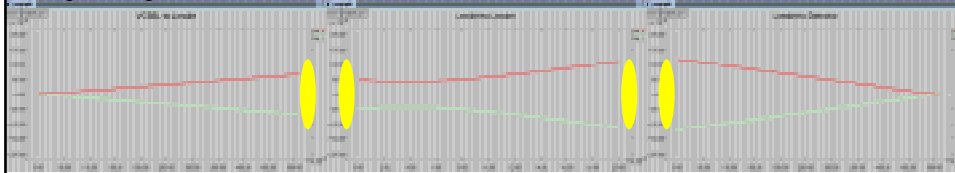
System Analysis with Different VCSEL Beam Divergence



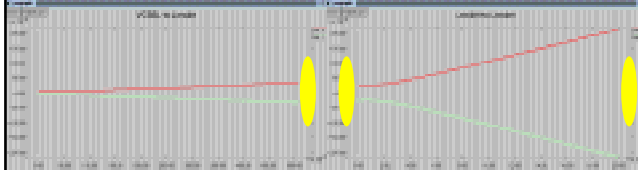
15 Degree Divergence



10 Degree Divergence



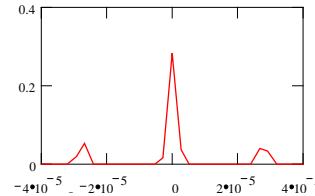
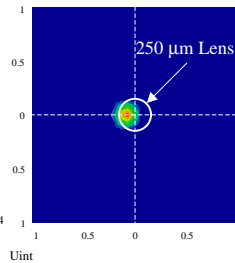
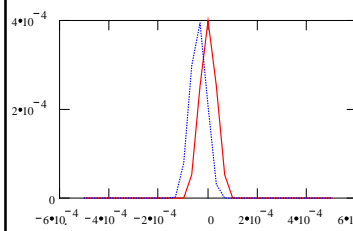
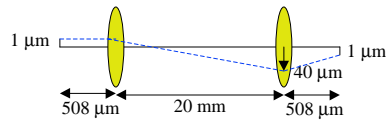
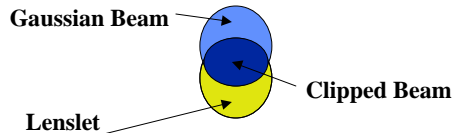
5 Degree Divergence



CAN NOT MODEL
NEED SCALAR MODELS...



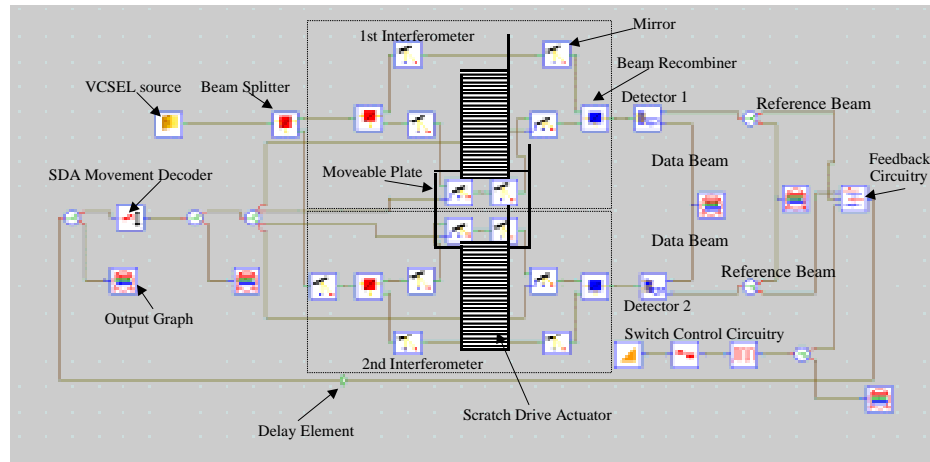
VCSEL 1 μm Mechanical Tolerancing - Scalar Analysis



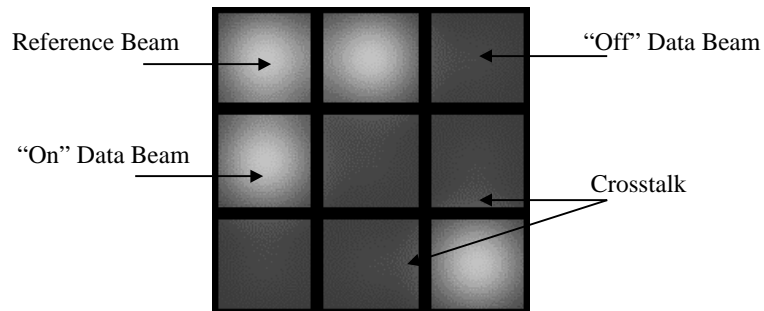
- At Second Lenslet Plane
- Blue is off-axis clipped beam
- Red is on-axis clipping
- Approximately 40 μm offset



System2: 1x2 Optical MEM Switch in *Chatoyant*



Static Result



- 56% System Efficiency
- -15.5 dB Crosstalk between neighbors
- With 1.0 Degree Offset, Efficiency Drops to 53.5%, Crosstalk Climbs to -11.42

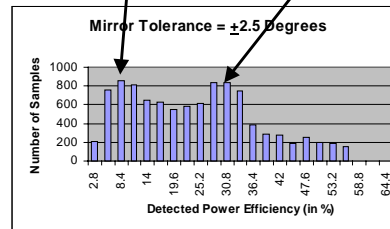
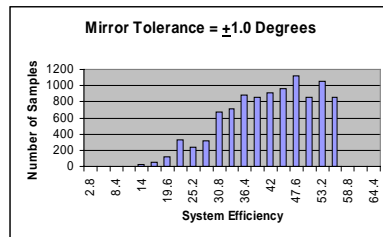


Monte Carlo Mechanical Tolerancing

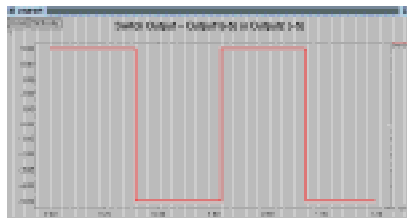


- Each mirror in interferometer has a tolerance range
- No mis-alignment produces a efficiency of 56%

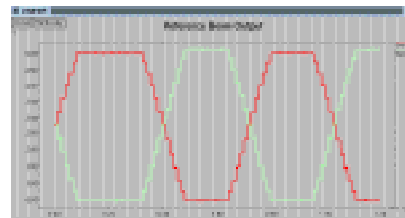
Crosstalk One Beam Detected



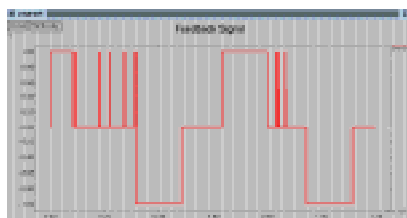
1x2 Switch Dynamic Outputs



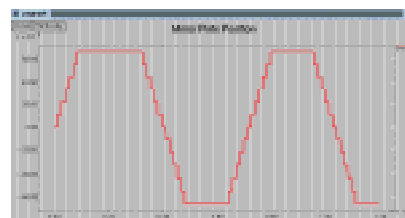
Switch Selection



Reference Beam



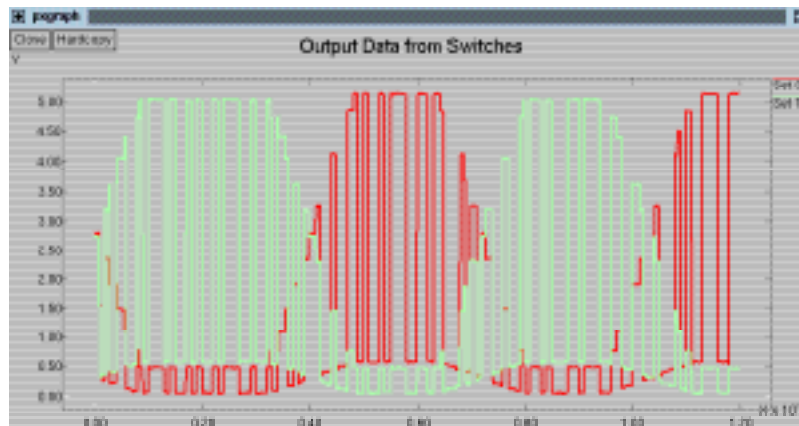
Feedback to SDA



Mirror Position



1x2 Switch Output



Chatoyant Development



- **New O/E Message Class**
- **Used New domain (DDF) for multi-rate systems**
- **Multi-platform (SunOS/Linux) support**
- **Use of TCL/TK Scripts for Monte Carlo Analysis**
- **VRML 3D Models**
- **Interfaces to/from low level electronic, optical, thermal & mechanical tools**
- **Non-sequential surfaces, multiple time bases, & multiple energy domains**
- **Ptolemy II???**