

# ***Real-Time Prototyping in Ptolemy***

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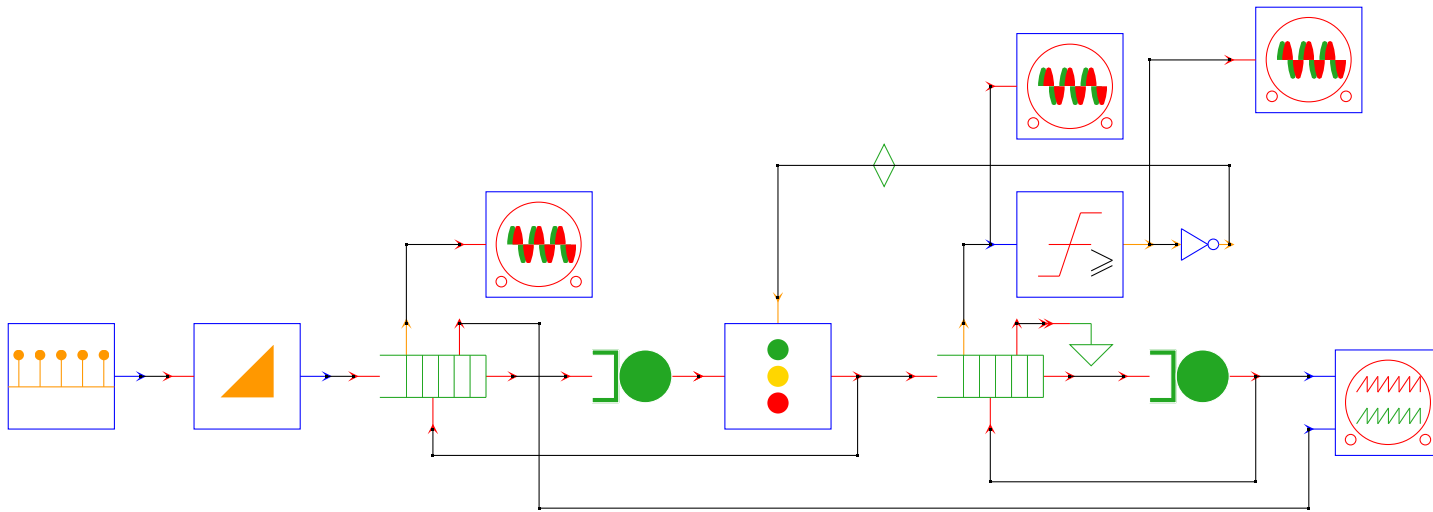
# *Objectives*

Provide a framework to:

- Specify systems using natural models of computation
- Use hardware within a simulation
- Use the user's computing environment
- Construct heterogeneous multiprocessor real-time prototypes
- ★ Shorten the **design cycle**

# *System Simulation*

- Interpreted — blocks compiled into Ptolemy system
- Multiple models of computation — process networks, communicating processes, discrete event, RTL



# Code Synthesis

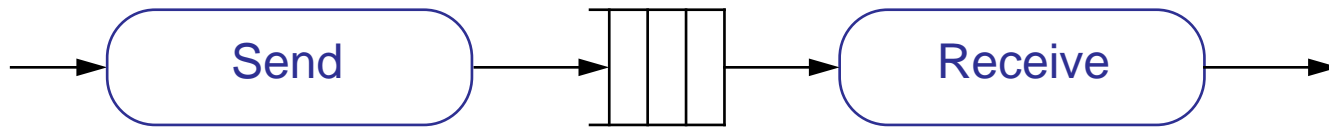
- Compile-time scheduling
- SDF & BDF models supported with extensions that allow for nondeterminate communication
- Object-oriented target specification



# Communication Actors

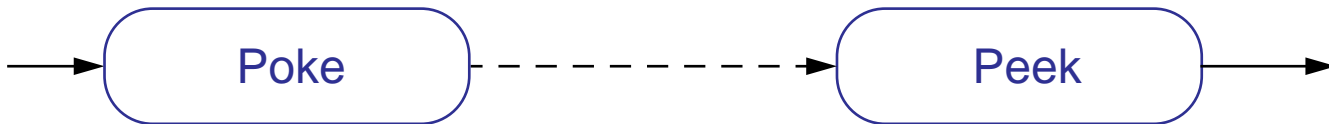
- Send/Receive

Multiprocessor self-timed SDF graphs

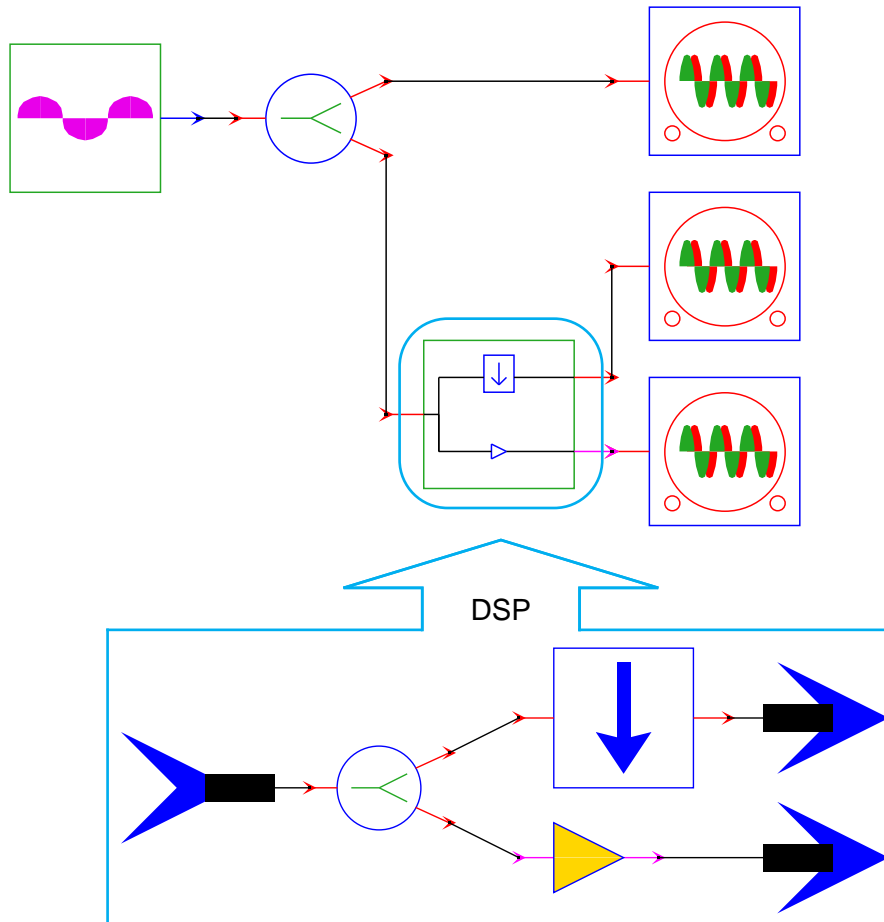


- Peek/Poke — Asynchronous & nondeterminate

Multiple independent SDF graphs

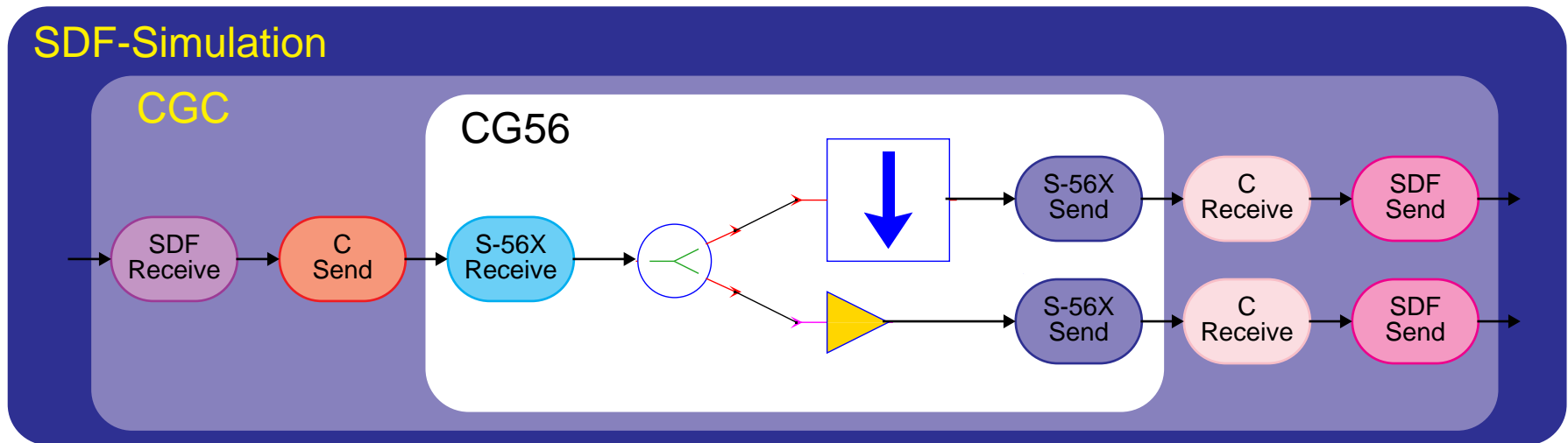


# Migration to Hardware



- Top level — runs using a Ptolemy simulation domain (SDF)
- Subsystem compiled, downloaded and run on a S-56X DSP board installed in a host workstation

# Simulation Interface Construction

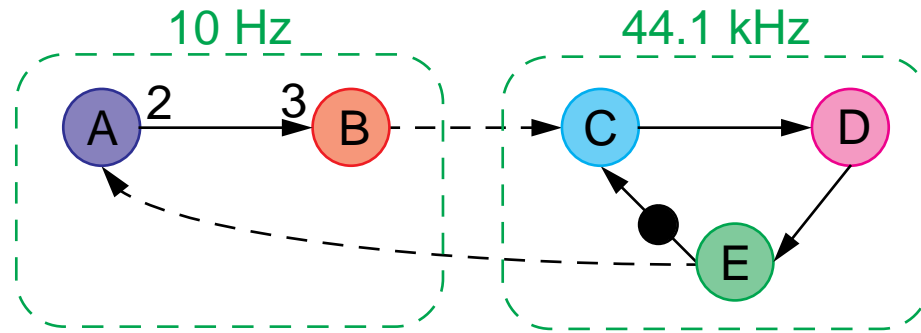


- Uses send/receive communication actors
- Incremental compilation
- Simulation block is constructed

# Stand-alone Prototype Synthesis

- Heterogenous multiprocessor support
- Hierarchical scheduling
- Peek/Poke — Extend SDF and BDF by allowing for nondeterminate communication
- Example of useful nondeterminism — real-time prototype user interfaces

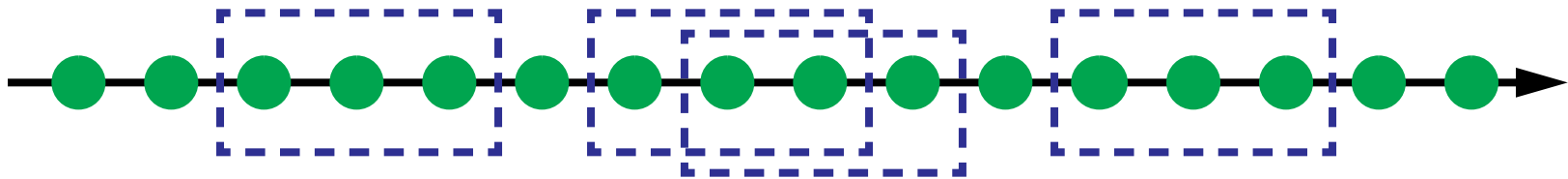
3(A)2(B)  
CDE



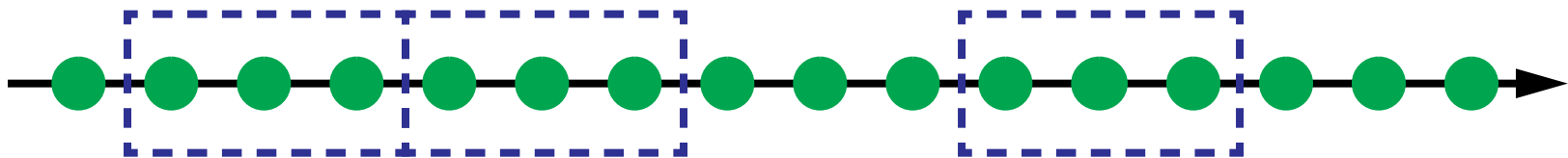


# *Peek/Poke Properties*

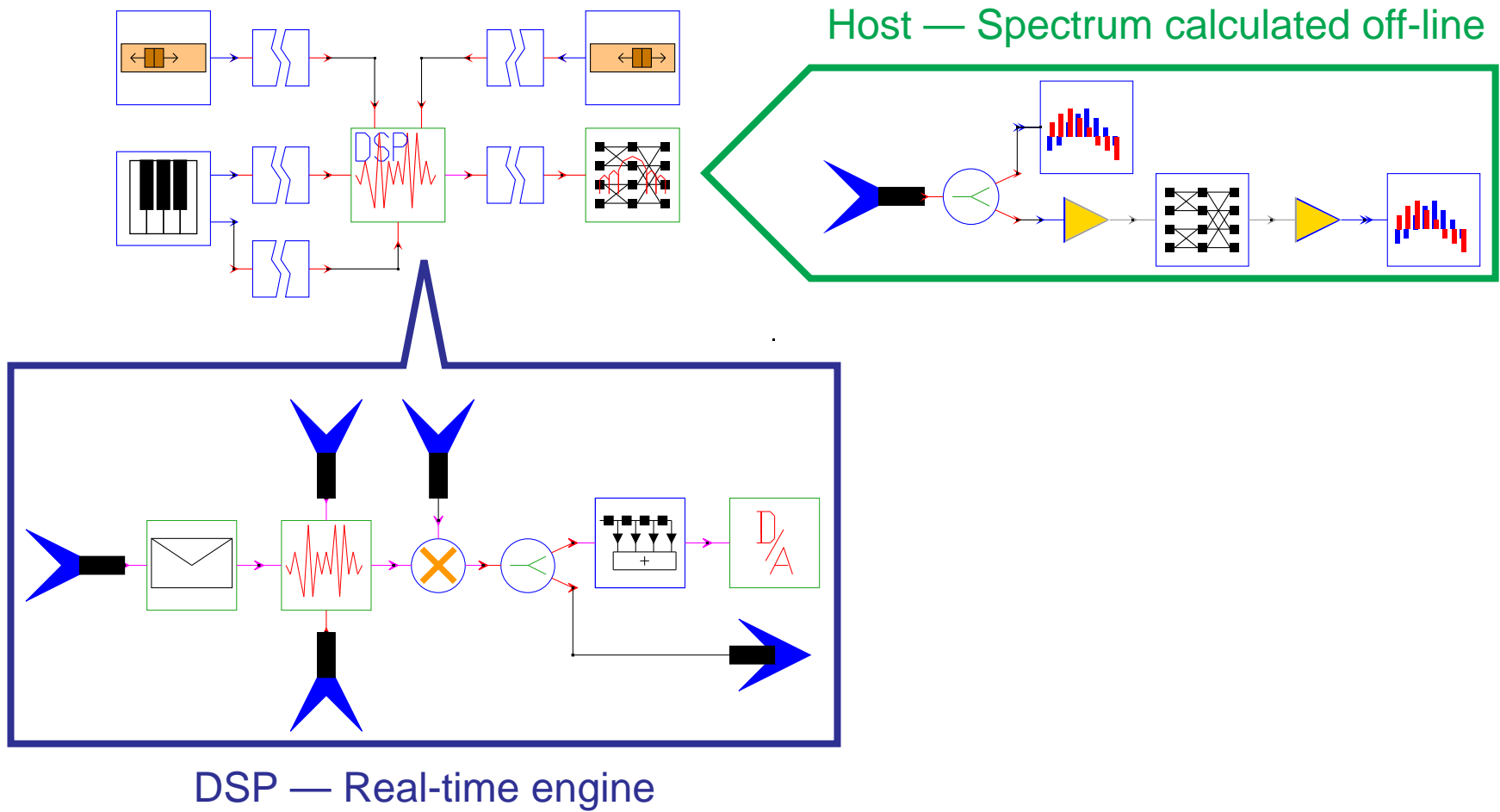
- Update rate is **explicit**, **implicit** or **event driven** (change of value)
- Single Sample
- Sliding Window



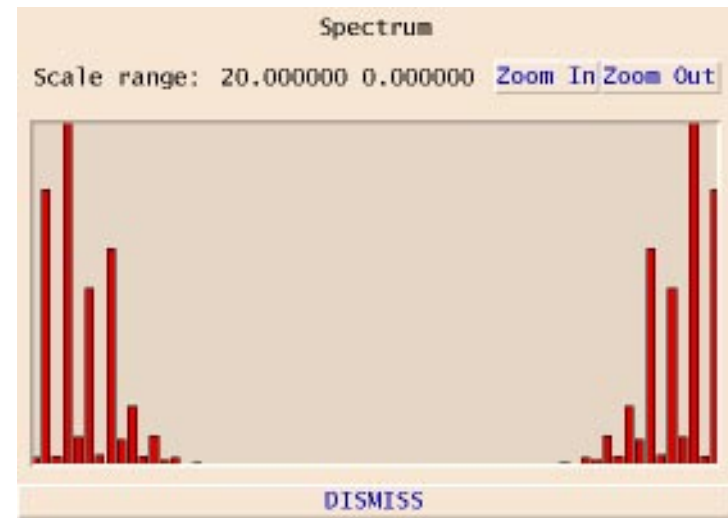
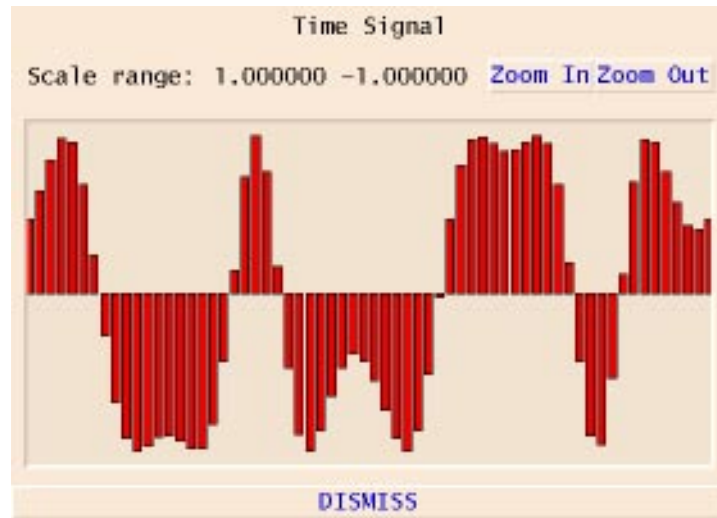
- Block aligned



# FM Synthesis Specification



# FM Synthesis: GUI



Control panel

[GO](#) <Return> [PAUSE](#) <Space> [STOP](#) <Escape>

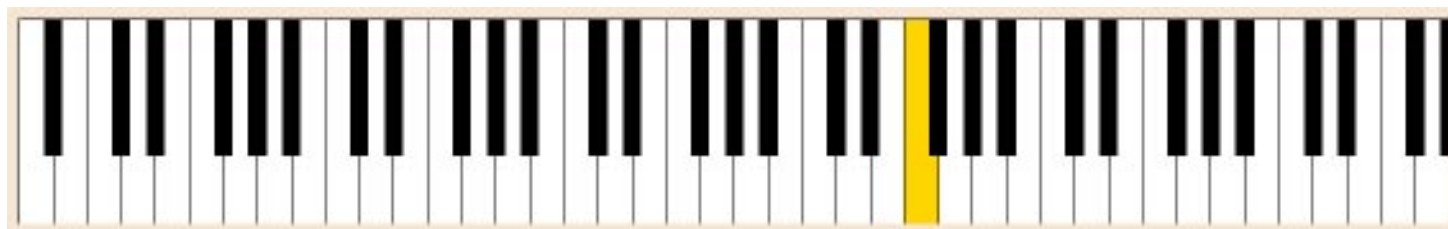
Number of Iterations:

Volume: 1.0000

FM\_Index: 0.7800

[QUIT](#)

The Control panel contains several controls: a row of buttons for GO (Return), PAUSE (Space), and STOP (Escape); a text input field for Number of Iterations (value: -1); two sliders for Volume (value: 1.0000) and FM\_Index (value: 0.7800); and a QUIT button.



# *Conclusions*

- Describe system with simulation domains
- Migrate subsystems to prototype hardware, generating a composite block for simulation which can be added to block library
- Generate a real-time stand-alone system using nondeterminate **peek/poke** communication actors as necessary